

This Mathematica Notebook contains computations and derivations used to create plots in Figs. 8, 9 and 10 of our paper Ohzawa, DeAngelis, Freeman, Encoding of Binocular Disparity by Complex Cells in the Cat's Visual Cortex, J. Neurophysiol. 77: 2879-2909, (1997).

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Monocular response (Left eye) of Cx cell based on the energy model is

$L_{resp}(xL) =$

$$(\text{Exp}[-k xL^2] \text{Cos}[2 \text{ Pi } xL])^2 + (\text{Exp}[-k xL^2] \text{Sin}[2 \text{ Pi } xL])^2$$

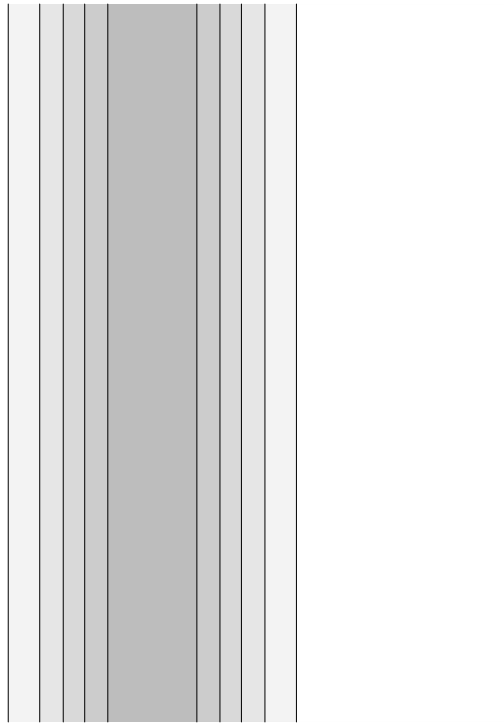
$$= (\text{Exp}[-k xL^2])^2$$

$$= \text{Exp}[-2 k xL^2]$$

k is proportional to the inverse of subunit RF width, and pD is the phase difference of L and R subunit RF fields (same for all 4 subunits).

Monocular response for the Left eye is given by,

```
z[x_]:=GrayLevel[1-x];
pD:= 0;
k:=5.5;
ContourPlot[
Exp[- 2 k xL^2]
,
{xL, -1, 1}, {xR, -1, 1},
Contours -> 12, PlotRange -> {0, 2.2},
ColorFunction -> z,
PlotPoints -> 40, Axes -> None, Frame -> False ]
```



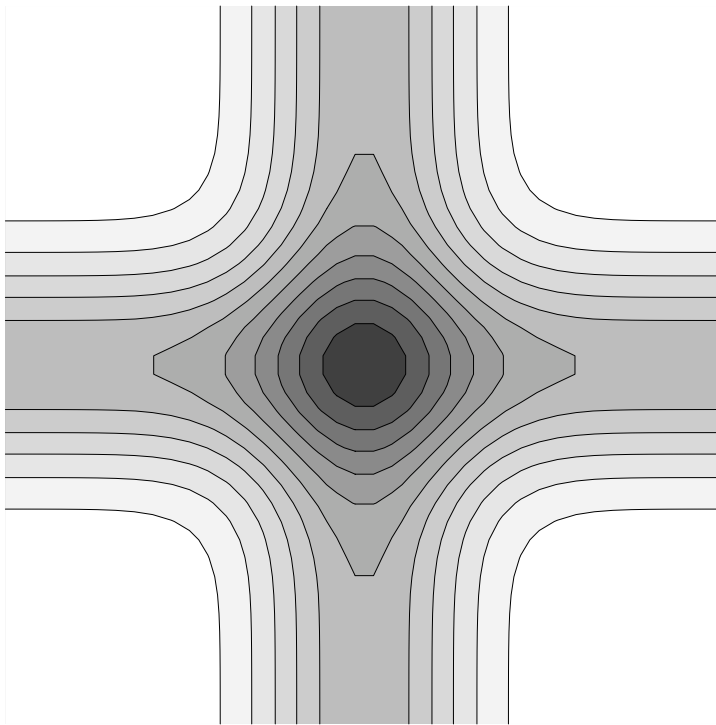
-ContourGraphics-

Sum of Left and Right monocular responses (which may be a good model for a non-phase specific cells) is given by:

```

z[x_]:=GrayLevel[1-x];
pD:= 0;
k:=5.5;
ContourPlot[
( Exp[- 2 k xL^2] + Exp[-2 k xR^2] )
,
{ xL, -1, 1}, { xR, -1, 1},
Contours -> 12, PlotRange -> {0, 2.2},
ColorFunction -> z,
PlotPoints -> 40, Axes -> None, Frame -> False ]

```



-ContourGraphics-

This is the derivation of Equation 7 from Equation 5 in our paper
 Ohzawa, DeAngelis, Freeman,
 Encoding of Binocular Disparity by Complex Cells in the Cat's Visual Cortex,
 J. Neurophysiol. 77: 2879-2909, (1997).

Binocular response for matched contrast conditions (BB and DD)
 may be simplified as follows:

$$\begin{aligned}
& \text{Simplify[} \\
& (\text{Exp}[-k \ xL^2] \ \text{Cos}[2 \ \text{Pi} \ F \ xL] + \text{Exp}[-k \ xR^2] \ \text{Cos}[2 \ \text{Pi} \ F \ xR + \text{pD}])^2 \\
& + (\text{Exp}[-k \ xL^2] \ \text{Sin}[2 \ \text{Pi} \ F \ xL] + \text{Exp}[-k \ xR^2] \ \text{Sin}[2 \ \text{Pi} \ F \ xR + \text{pD}])^2 \\
&] \\
& \frac{E^{-2k \ xL^2} + E^{-2k \ xR^2} + 2 \ \text{Cos}[\text{pD} - 2 \ F \ \text{Pi} \ xL + 2 \ F \ \text{Pi} \ xR]}{E^k (xL^2 + xR^2)}
\end{aligned}$$

Just to be general, try the case where spatial freq are different between L and R eyes (use FL and FR for each eye).

$$\begin{aligned}
& \text{Simplify[} \\
& (\text{Exp}[-k \ xL^2] \ \text{Cos}[2 \ \text{Pi} \ \text{FL} \ xL] \\
& \quad + \text{Exp}[-k \ xR^2] \ \text{Cos}[2 \ \text{Pi} \ \text{FR} \ xR + \text{pD}])^2 \\
& + (\text{Exp}[-k \ xL^2] \ \text{Sin}[2 \ \text{Pi} \ \text{FL} \ xL] \\
& \quad + \text{Exp}[-k \ xR^2] \ \text{Sin}[2 \ \text{Pi} \ \text{FR} \ xR + \text{pD}])^2 \\
&] \\
& \frac{E^{-2k \ xL^2} + E^{-2k \ xR^2} + 2 \ \text{Cos}[\text{pD} - 2 \ \text{FL} \ \text{Pi} \ xL + 2 \ \text{FR} \ \text{Pi} \ xR]}{E^k (xL^2 + xR^2)}
\end{aligned}$$

As shown above, the first two terms are monocular responses. The last term is the binocular interaction component, which is a Gabor function (Is this really a Gabor?) that is oriented at 45 degs in (xL, xR) domain (see below).

The binocular component alone may be obtained without separate monocular measurements by computing BB+DD-BD-DB. Since BB == DD and BD == DB, because of squaring which makes the function independent of the inversion of sign,

$$BB+DD-BD-DB = 2 (BB-BD)$$

BB-BD is given by below which is reduced the same expression as above.

```

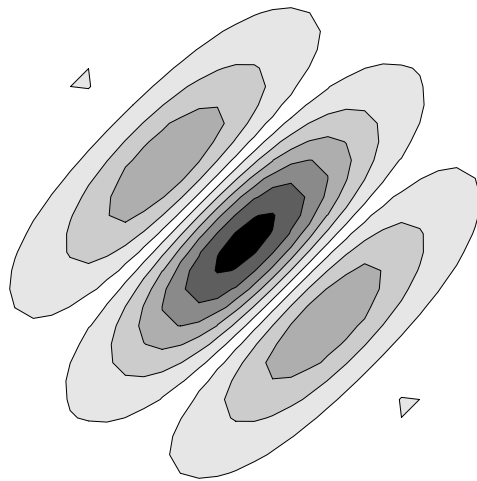
k=. ;
pD=. ;
Simplify[
(Exp[-k xL^2] Cos[2 Pi xL] +Exp[-k (xR)^2] Cos[2 Pi (xR) + pD])^2
+(Exp[-k xL^2] Sin[2 Pi xL] +Exp[-k (xR)^2] Sin[2 Pi (xR) + pD])^2
- (
(Exp[-k xL^2] Cos[2 Pi xL] -Exp[-k (xR)^2] Cos[2 Pi (xR) + pD])^2
+(Exp[-k xL^2] Sin[2 Pi xL] -Exp[-k (xR)^2] Sin[2 Pi (xR) + pD])^2
) ]

```

$$\frac{4 \cos[pD - 2 \pi xL + 2 \pi xR]}{E^k (xL^2 + xR^2)}$$

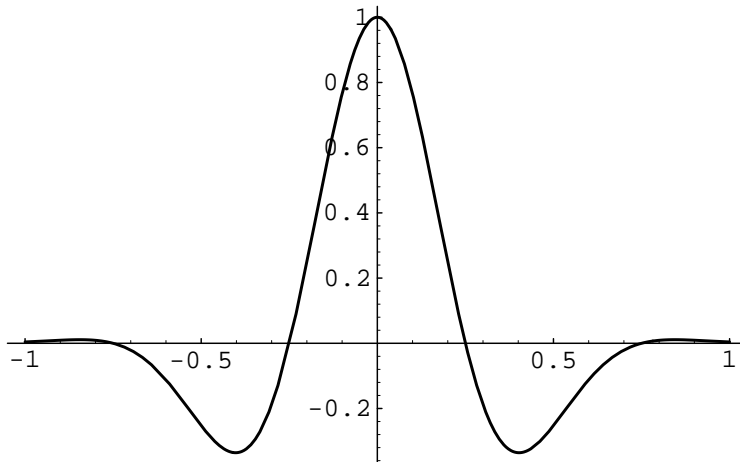
This is a Gabor function oriented at 45 degs in the (xL, xR) domain as shown below: (ModelDecomp/GaborLR-0.eps)

```
z[x_]:=GrayLevel[1-2*Abs[x-0.5]];
pD:= 0;
k:=5.5;
ContourPlot[
  Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {-1.1, 1.1},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

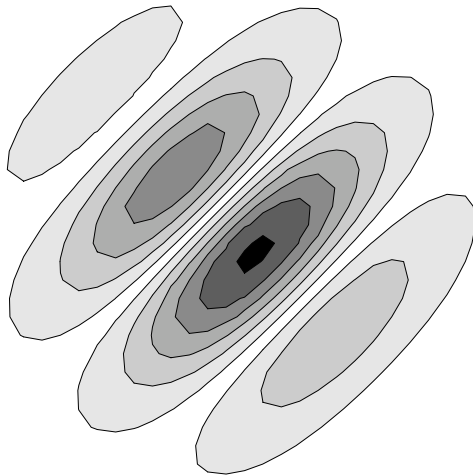
```
k:=5.5;  
Plot[  
  Exp[-k (xL^2)] Cos[2 Pi xL],  
  {xL, -1, 1},  
  PlotPoints -> 40 ]
```



-Graphics-

Phase Difference = 45 degs (ModelDecomp/GaborLR-45.eps)

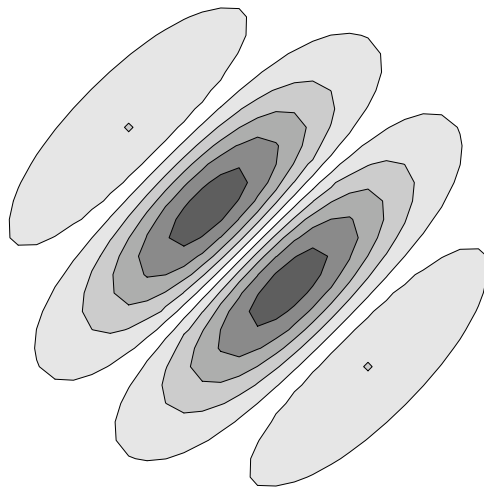
```
z[x_]:=GrayLevel[1-2*Abs[x-0.5]];
pD:= Pi/4;
k:=5.5;
ContourPlot[
  Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {-1.1, 1.1},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

Phase Difference = 90 degs (ModelDecomp/GaborLR-90.eps)

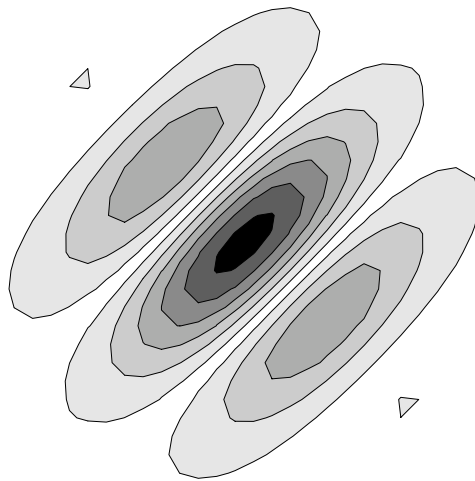

```
z[x_]:=GrayLevel[1-2*Abs[x-0.5]];
pD:= Pi/2;
k:=5.5;
ContourPlot[
  Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {-1.1, 1.1},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

Phase Difference = 180 degs (ModelDecomp/GaborLR-180.eps)

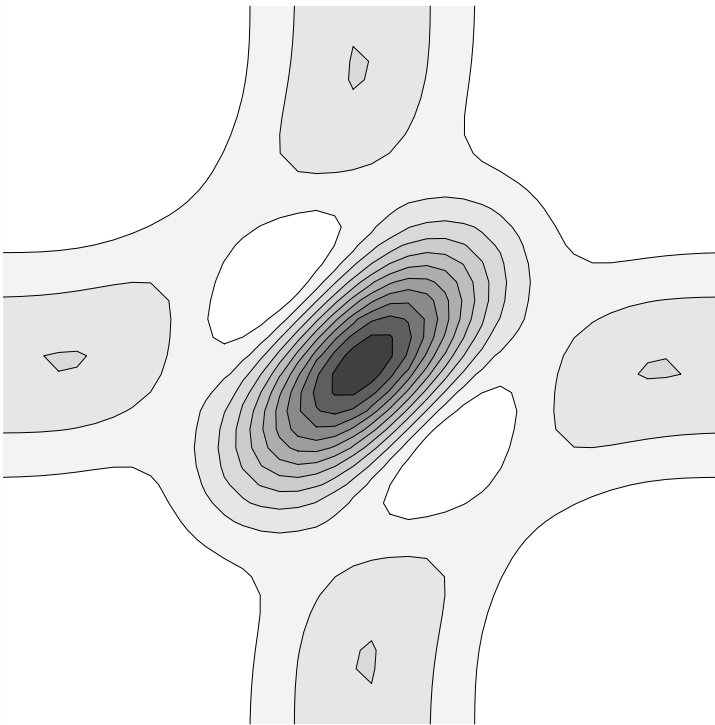
```
z[x_]:=GrayLevel[1-2*Abs[x-0.5]];
pD:= Pi;
k:=5.5;
ContourPlot[
  Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {-1.1, 1.1},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

Zero disparity detector for both phase and position models
is the same:

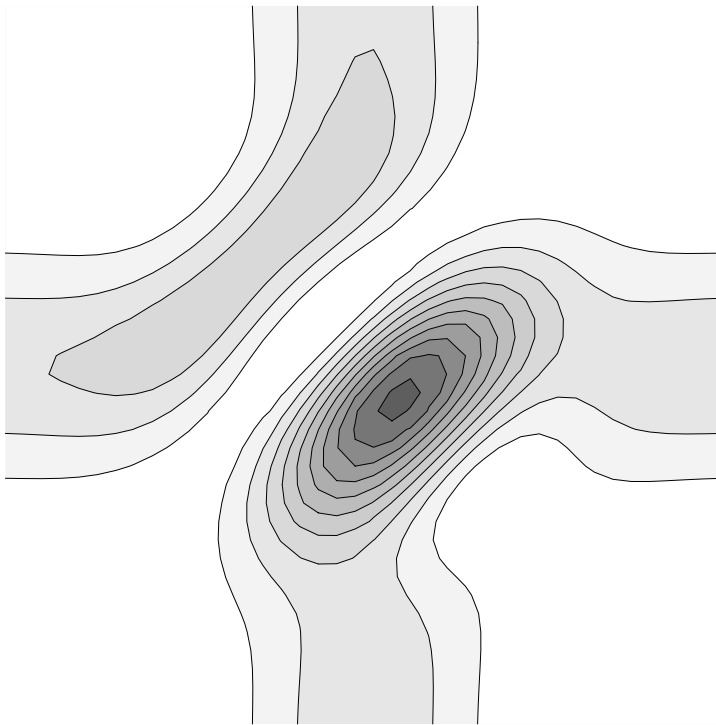
```
z[x_]:=GrayLevel[1-x];
pD:= 0;
k:=5.5;
ContourPlot[
  Exp[- 2 k xL^2] + Exp[-2 k xR^2]
+ 2 Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {0, 4.4},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

Non-Zero disparity detector for the phase model

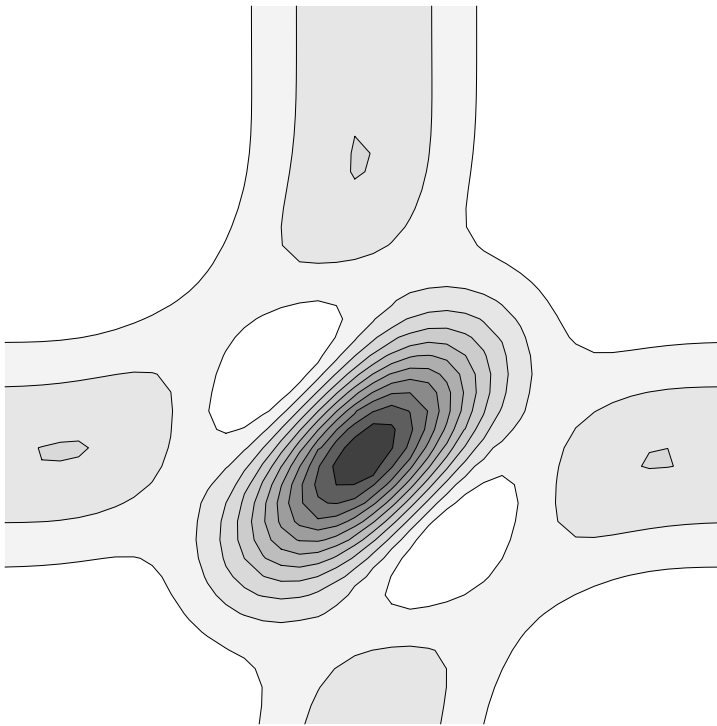
```
z[x_]:=GrayLevel[1-x];
pD:= Pi/2;
k:=5.5;
ContourPlot[
  Exp[- 2 k xL^2] + Exp[-2 k xR^2]
+ 2 Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {0, 4.4},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

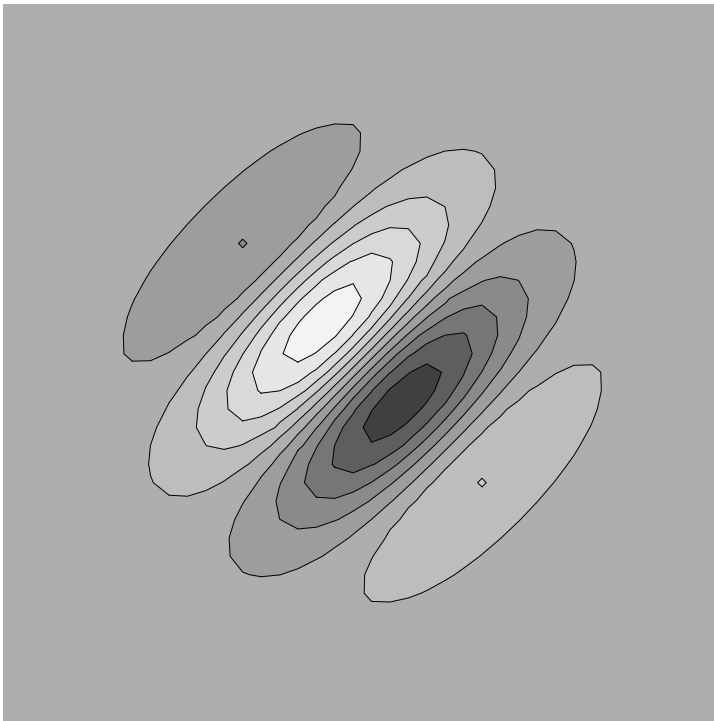
Non-Zero disparity detector for the Position model

```
z[x_]:=GrayLevel[1-x];
oR:= 0.25;
pD:= 0;
k:=5.5;
ContourPlot[
  Exp[- 2 k xL^2] + Exp[-2 k (xR+oR)^2]
+ 2 Exp[-k (xL^2 + (xR+oR)^2)] Cos[2 Pi (xL - (xR+oR)) - pD],
  {xL, -1, 1}, {xR, -1, 1},
  Contours -> 12, PlotRange -> {0, 4.4},
  ColorFunction -> z,
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-

```
z[x_]:=GrayLevel[1-x];  
pD:= Pi/2;  
k:=5.5;  
ContourPlot[  
  Exp[-k (xL^2 + xR^2)] Cos[2 Pi (xL - xR) - pD],  
  {xL, -1, 1}, {xR, -1, 1},  
  Contours -> 12, PlotRange -> {-1.1, 1.1},  
  ColorFunction -> z,  
  PlotPoints -> 40, Axes -> None, Frame -> False ]
```



-ContourGraphics-